

# Discovering Structures in Gene Regulatory Networks Using Genetic Programming and Particle Swarms

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## ABSTRACT

In this paper, we describe a genetic programming and particle swarm hybrid algorithm for gene network discovery.

## Categories and Subject Descriptors

I.2.8 [Artificial Intelligence]: Problem Solving, Control Methods and Search – *graph and tree search strategies, heuristic methods.*

## General Terms

Algorithms, Theory.

## Keywords

Genetic programming, gene regulatory networks, clonal selection, particle swarm optimization, bioinformatics.

## 1. PROBLEM DEFINITION

Synthetic data were generated for this problem based on temperatures and day lengths from 18 European sites [1]. The data represented the day of the year that the first inflorescence bud would become visible for *Arabidopsis thaliana* plants shown on each of three different dates *ca.* one month apart.

The goal is to obtain a simplified genetic network whose model bolting dates would be as close to the synthetic data as possible. Synthetic bolting dates are predicted by a particular model structure for the  $i^{\text{th}}$  combination of genotype, geographic site, and planting date.

The genes in the model genetic network are allowed to implement any of the following four functions: (i) *gain*:  $o = c_g \cdot i_1$ , (ii) *summer*:  $o = c_s \cdot i_1 + i_2$ , (iii) *multiplier*:  $o = c_m \cdot i_1 \cdot i_2$ , and (iv) *integrator*:  $c_i$ , i.e.  $o(t) = o(t-1) + c_i \cdot i_1(t)$ . In each case,  $i_1$  and  $i_2$  are the inputs and  $o$  the output. Each gene has a single parameter associated with it ( $c = c_g, c_s, c_m$  or  $c_i$ ). These parameters are assigned two separate numerical values, one for each allele. The inputs to each gene can be either the outputs from other genes in the network, or environmental, i.e. photoperiod or temperature.

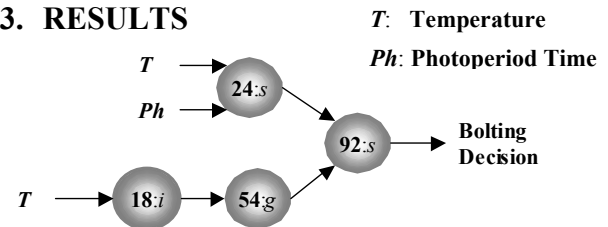
## 2. APPROACH

Genetic Programming is used for network representation. Each solution is represented in the form of a string containing fields equal in number to that of putative network genes. Each field

contains four entries - the two gene inputs, an entry representing gene function ( $g, s, m, \text{ or } i$ ), and an index identifying the gene in the data that this particular field in the string represents.

The optimization algorithm to discover the gene network's structure is based on clonal selection [2]. To estimate the parameters ( $c_g, c_s, c_m$  or  $c_i$ ) of the network's genes, particle swarm optimization (PSO) is applied [3]. In each iteration, the fitnesses of each network in the population is computed by estimating its parameters through PSO. The solutions obtained are cloned based on their ranks. Each clone is then mutated and its fitness computed based on PSO. The best solutions from all the original networks and the clones are retained and the rest discarded.

## 3. RESULTS



$$\text{Bolting}(t) = C_{92} * (C_{24} * T(t) + Ph(t)) + C_{54} * (C_{18} * \sum_{n=0}^t T(n))$$

Figure 1. One of gene structures we found and its mathematical expression

Figure 1 shows a gene network obtained by our algorithm. It has correct genes and two-pathway. The real *Arabidopsis thaliana* network, after which this system is modeled, consists of four pathways, two of which mediate responses to features not considered here.

## 4. REFERENCES

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